## FTR - Flight Test Report Dieser Prüfbericht darf ohne schriftliche Zustimmung der EAPR nicht, auch nich

Manufacturer		Type testing No.	EAPR-GS-0766/18
	UP International  Kreuzeckbahnstraße 7 D-82462 Garmisch-Partenkirchen	serial number	XA61582-02-1178-7294#RE/1
Model	Ascent-4 M	Lagation	Schlick, Stubaital
Comment		Location	Rofan, Achensee



Rev. 2.3 - 26.11.2014 EAPR GmbH - Marktstr. 11 D-87730 Bad Grönenbach - Germany

Date of testing	20.12.2017	Minimum take 80 kg		Maximum take off weight 110 kg			
Testpilot		Johannes Tschofer	1	Anselm Rauh			
Harness		EAPR leicht		EAPR light			
Pilot's take off weigh	t	80	kg	108	kg		

Classification

Α



Test-criteria		Minimum take off weight	Evaluation	Maximum take off weight	Evaluation	
1. Inflation / take-off - 4.4.1						
Rising behavior		no pilot correction required	Α	no pilot correction required	А	
Special take off technique required		No	А	No	А	
2. Landing - 4.4.2		1	, ,	1	, , ,	
Special landing technique required		I No	l A	No	A	
3. Speeds in straight flight - 4.4.3		1.0		1.0		
Trim speed more than 30km/h		Yes	A	Yes	l A	
Speed range using the controls larger than 10km/h	1	Yes	A	Yes	A	
					A	
Minimum speed  4. Control movement - 4.4.4		Less than 25 km/h	A	A Less than 25 km/h		
Max. weight in flight up to 80kg						
wax. weight in hight up to boxg			-		_	
Max. weight in flight 80 to 100kg		-			-	
Max. weight in flight greater than 100kg		Increasing >65 cm	Α	Increasing >65 cm	Α	
5. Pitch stability exiting accelerated flight - 4.4	1.5					
Dive forward angle on exit		Dive forward less than 30°	Α	Dive forward less than 30°	Α	
Collapse occurs		No	Α	No	Α	
6. Pitch stability operating controls during acc	elerated	flight - 4.4.6				
Collapse occurs		No	Α	No	Α	
7. Roll stability and damping - 4.4.7						
Oscillations		Reducing	A	Reducing	А	
8. Stability in gentle spirals - 4.4.8						
Tendency to return to straight flight		Spontaneous exit	l A	Spontaneous exit	Α	
9. Behaviour exiting a fully developed spiral di	ive - 4.4.	9	,			
Initial response of glider (first 180°)		Immediate reduction of rate in turn	l A	Immediate reduction of rate in turn	А	
Tendency to return to straight flight				A Spontaneous exit		
Turn angle to recover normal flight		Less than 720°, spontaneous recovery	Α	Less than 720°, spontaneous recovery	Α	
10. Symmetric front collapse - 4.4.10			<u> </u>			
Folding lines used		I No		No		
Entry	*	Rocking back less than 45°	А	Rocking back less than 45°	А	
Recovery	%0c ~ pa	Spontaneous in less than 3 sec	Α	Spontaneous in less than 3 sec	Α	
Dive forward angle on exit	paeds	0° - 30° Keeping course	Α	0° - 30° Keeping course	Α	
Cascade occurs	trim	No	А	No	Α	
Entry	%0	Rocking back less than 45°	Α	Rocking back less than 45°	Α	
Recovery	%05 < beek	Spontaneous in less than 3 sec	Α	Spontaneous in less than 3 sec	А	
Dive forward angle on exit		0° - 30° Keeping course	А	0° - 30° Keeping course	А	
Cascade occurs	mi/4	No	Α	No	Α	
Entry	%0%	Rocking back less than 45°	Α	Rocking back less than 45°	Α	
Recovery	elerated > 50%	Spontaneous in less than 3 sec	Α	Spontaneous in less than 3 sec	Α	
Dive forward angle on exit	celera	0° - 30° Keeping course	Α	0° - 30° Keeping course	Α	
Cascade occurs	aoce	No	Α	No	Α	
11. Exiting deep stall (parachutal stall) - 4.4.11	1					
Deep stall achieved		Yes		Yes		
Recovery		Spontaneous in less than 3 sec	А	Spontaneous in less than 3 sec	Α	
Dive forward angle on exit		0° - 30°	Α	0° - 30°	А	
Change of course			A	Changing course less than 45°	A	
Cascade occurs		Changing course less than 45° No	A	No		

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12. High angle of attack recovery - 4.4.12									
Recovery					А	Spontaneous in	Α		
Cascade occurs	·		No			No			Α
13. Recovery from a developed full stall - 4.4.13					Α				
Dive forward angle on exit		0° - 30°			A A	0° - 30°			A
Collapse Cascade occurs (other than collapse)		No collapse No			Α	No collapse No			Α
Rocking backward		Less than 45° Most lines tight		-	A A	Less than 45° Most lines tight		-	A
Line tension  14. Asymmetric collapse (trim speed) - 4.4.14		Wost intes tight			А	Most lines tight			А
Folding lines used		No				No			
Change of course until re-inflation	Ф	< 90°	Dive or roll angle	15° - 45°	Α	< 90°	Dive or roll angle	0° - 15°	Α
Re-inflation behavior	ed, Illaps	Spontaneous re	-inflation		Α	Spontaneous re	-inflation		Α
Total change of course	trim speed, max 50% collapse	Spontaneous re-inflation  Less than 360°			A	Less than 360°			A
Collapse on the opposite side occurs	trim tx 50	No			A	No			A
Twist occurs Cascade occurs	ű.	No No			A	No No			A
Change of course until re-inflation		< 90°	Dive or roll angle	15° - 45°	A	< 90°	Dive or roll angle	15° - 45°	A
Change of course until re-initation	apse	V 90	Dive or roll angle	13 - 43	^	V 30	Dive or roll arigie	13 - 43	^
Re-inflation behavior	trim speed, max 75% collapse	Spontaneous re	-inflation		Α	Spontaneous re	-inflation		Α
Total change of course	trim sl x 75%	Less than 360°			A	Less than 360° No No No No			A
Collapse on the opposite side occurs Twist occurs	t max	No No		A	A				
Cascade occurs		No No			Α				Α
Change of course until re-inflation		< 90°	Dive or roll angle	15° - 45°	Α	< 90°	Dive or roll angle	0° - 15°	А
	ad, lapse							· · · · · ·	
Re-inflation behavior	accelerated, max 50% collapse	Spontaneous re	-ıntlation		A	Spontaneous re	-ıntlation		A
Total change of course  Collapse on the opposite side occurs	3ccel	Less than 360° No			A	Less than 360° No			A
Twist occurs	ma	No			Α	No			Α
Cascade occurs		No			A	No			A
Change of course until re-inflation	986	< 90°	Dive or roll angle	15° - 45°	Α	< 90°	Dive or roll angle	15° - 45°	Α
Re-inflation behavior	ated, collap	Spontaneous re	-inflation		Α	Spontaneous re	-inflation		Α
Total change of course	accelerated x 75% colla	Less than 360°			Α	Less than 360°			Α
Collapse on the opposite side occurs Twist occurs	ac nax 7	Spontaneous re-inflation Less than 360° No No No			A	No No No			A
Cascade occurs					A				A
15. Directional control with a maintained asymmetry	metric col	-							
Able to keep course straight		Yes			Α	Yes			Α
180° turn away from the collapsed side possible in	10 sec	Yes			Α	Yes			Α
Amount of control range between turn and stall or s	More than 50% of the symmetric control travel			Α	More than 50%	Α			
16. Trim speed spin tendency - 4.4.16									
Spin occurs	No No			A			No		
17. Low speed spin tendency - 4.4.17									
Spin occurs		No			A No				Α
18. Recovery from a developed spin - 4.4.18						l a			
Spin rotation angle after release		Stops spinning in less than 90°			Α	Stops spinning in less than 90°			A
Cascade occurs  19. B-line-stall - 4.4.19		No			А	No			А
Change of course before release		Changing course	e less than 45°		А	Changing course	e less than 45°		А
Behaviour before release		Changing course less than 45°  Remains stable with straight span		A	Remains stable with straight span			A	
Recovery		Spontaneous in less than 3 sec		Α	Spontaneous in less than 3 sec			Α	
Dive forward angle on exit Cascade occurs			0° - 30° No		A	0° - 30° No			A
20. Big ears - 4.4.20									
Entry procedure		Standard technique			А	Special device r	equired		А
Behaviour during big ears		·		A	Stable flight			A	
		Stable flight			A				A
Recovery		Spontaneous in less than 3 sec  0° - 30°			A	Spontaneous in less than 3 sec  0° bis 30°			A
Dive forward angle on exit  21. Big Ears in accelerated flight - 4.4.21		0 - 30			, A	0 015 30-			, A
				Α	Special dovice	equired		А	
intry procedure		Standard technique		A	Special device required			A	
Behaviour during big ears		Stable flight		A	Stable flight			A	
Recovery  Dive forward angle on exit		Spontaneous in less than 3 sec  0° - 30°			Spontaneous in less than 3 sec				
Dive forward angle on exit  Behaviour immediately after releasing the accelarator while		Stable flight		A	0° bis 30° Stable flight		A		
maintaining big ears Stable flight					JIANE IIIGIII				
23. Alternative means of directional control - 4.4.22									
180° turn achievable in 20 sec	Yes			Α	Yes			Α	
						А			
23. Any other flight procedure and/or configuration of the procedure works as descibed	ation desc	cribed in the user	's manual - 4.4.2	23	NA	1			NA
Procedure suitable for novice pilots				NA				NA	
Cascade occurs				NA				NA	
24. Remarks of testpilot:									
ı		L				L			

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